

# Development of a Wearable HRV Telemetry System to be Operated by Non-Experts in Daily Life

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**Abstract**—A telemetry system for the measurement of heart rate variability (HRV) with automatic gain control has been developed with a low-cost manufacturing process and a low-power consumption design. The proposed automatic gain control technique provided highly reliable RR interval (RRI) detection for subjects of different ages, and enabled the subjects to use the system without any expert knowledge of the electrocardiogram (ECG) measurement. All the components and functions for the RRI measurement were implemented on a wearable telemeter which can operate for up to 440 h with a CR2032 coin battery, and the wirelessly transmitted RRI data is stored into a PC by a receiver via a USB connection. The errors of the RRI detection occurred at less than 2% probability in subjects of five different ages. In a long-term measurement of a young subject that extended over 48 h, the results showed a 0.752% probability of recurring errors. The obtained results suggest that the proposed system enables the long-term monitoring of HRV for both clinical care and healthcare operated by a non-expert.

## I. INTRODUCTION

Low cost methods of vital sign monitoring are in demanded because the healthcare costs are rapidly increasing. For the purpose of early detection of diseases and acute symptoms, long-term monitoring of the electrocardiogram (ECG) delivers beneficial evidences in both clinical care and homecare. The analysis of heart rate variability (HRV), which is calculated from the R-R intervals (RRI), gives diagnostic evidences of arrhythmia [1], chronic obstructive pulmonary disease [2], and others [3]. From the point of view of hardware implementation, the measurement system of the RRI can be realized by a simple circuit architecture that does not require power-consuming components such as analog-to-digital converters, and thus may reduce the size and power consumption of the measurement device in comparison with the full scale ECG measurement system.

The development of an HRV telemetry system described in this paper has been aimed for simple use, i.e., high mobility, and high accuracy detection of RRI. This telemeter is regarded as a consumer friendly device that can be commercially available at low cost and used by any subject

without expert knowledge in ECG measurement. The telemetry system could be a supportive monitoring device because the collected data can be transferred as files of low size into the hospital's monitoring system to obtain an immediate diagnosis.

The measurement of RRI at different sex and ages can be achieved by the automatic gain control system that is capable of adjusting the gain automatically for different subjects. The embedded programs play important roles in the high accuracy detection of R waves and the quick adjustment of gain for ECG amplification. The ECG measurement performed at home is an ideal financial aid for patients and even for healthy people for the purpose of health promotion and early detection of diseases. Because the device is used by the patients at home, the important matter to be considered is the low cost, easy usage, and long life with a modest measurement performance. To confirm that the proposed system satisfies the above requirements, the experiment was directed to the analysis of the function of the automatic gain control and the accuracy of long-term measurements.

## II. SYSTEM DESCRIPTION

The proposed telemetry system consists of two devices: the RRI telemeter and a receiver. The RRI telemeter measures ECG, detects the R waves from the ECG, and transmits the RRI data through an 868 MHz GFSK bidirectional wireless communication. The receiver receives and demodulates the wireless signal from the telemeter, and stores it into a PC through a USB connection. The details of the devices are explained in the following subsections.

### A. Hardware constitution of the RRI Telemeter

Figures 1 (a) and (b) show the block diagram of the proposed RRI telemeter and the circuit diagram of the analog frontend, respectively. The ECG measured by three electrodes (+, -, GND) is amplified and conditioned in the analog frontend. To achieve the single power supply of a 3-V battery CR2032, the common-mode feedback (CMFB) structure is

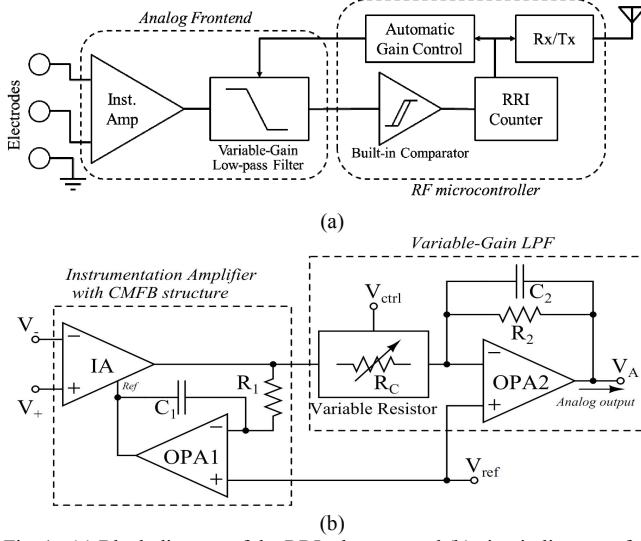


Fig. 1. (a) Block diagram of the RRI telemeter and (b) circuit diagram of the analog frontend.

adopted for the differential signal amplification as shown in the left dashed rectangle in Fig. 1 (b). Using this structure, the output common-mode voltage of the instrumentation amplifier is set to  $V_{ref}$ , which is the reference voltage made by a resistor chain. The first-order variable-gain active low-pass filter (LPF) was designed to reduce the high-frequency noise of  $>38$  Hz. The gain is defined by the resistor ratio  $R_2/R_C$ , where  $R_C$  is the resistor value of the variable resistor. Here  $R_C$  is controlled by the automatic gain control program that is embedded in the microcontroller, as described later. Though this LPF may reduce the amplitude of the R waves, a sufficient amplitude is obtained because it is adequately amplified due to the automatic gain control. The output common-mode voltage of the analog frontend is set to  $V_{ref}$  because the positive nodes of OPAs are connected to  $V_{ref}$ . Here,  $V_{ref}$  of 2.49 V was obtained with a resistor chain. The current dissipation of the analog frontend was kept under approximately 80  $\mu$ A by adopting the following low power ICs: INA122 for the instrumentation amplifier, MCP6042 for OPAs, and MCP4011 for the variable resistor.  $R_1$  of 1  $M\Omega$ ,  $R_2$  of 1  $M\Omega$ ,  $C_1$  of 1  $\mu$ F, and  $C_2$  of 4.7 nF were used in this prototype fabrication.

The output of the analog frontend was connected to an input node of an RF microcontroller (CC430F5137) as shown in Fig. 1 (a). This input node is observed by the built-in comparator, and the comparator outputs the positive pulse, lower than 1.5 V, during the input signal. In other words, the amplified ECG signal whose amplitude is larger than 0.99 V ( $=V_{ref} - 1.5$ ) is extracted as an R wave candidate. The R wave candidates are treated by the embedded program as described in the following subsections.

### B. Embedded Programs and Automatic Gain Control

A quasi band-pass filtering (BPF) program and the R wave detection program were installed in the microcontroller. The BPF program counts the pulse width of the R wave candidate, which is obtained by the comparator, and forwards the signal

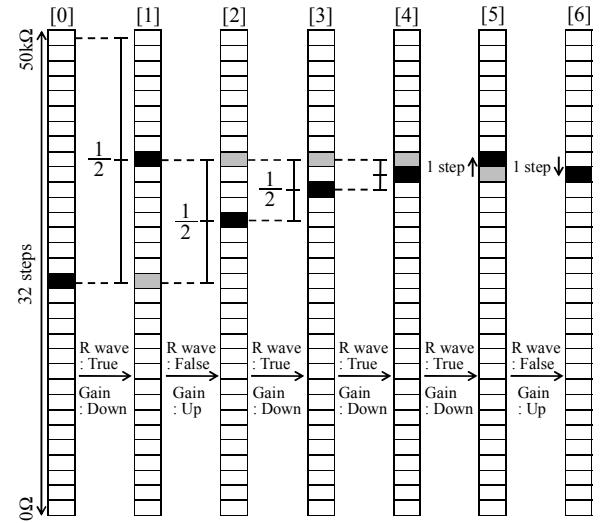


Fig. 2. Example of the proposed AGC scheme. The black cells and the gray cells show the selected  $R_C$  values and the previous  $R_C$  values, respectively.

only when the pulse width is in the range of 3–50 ms to compress the noises (e.g., HF noise originated in the poor hysteresis of the comparator and wide ECG pulses such as P or T waves). The RRI counter stores the timer values of the R wave occurrence and the RF transmission as described in the following subsection.

The amplitude of the ECG can be reduced due to the electrode alignment, the condition between the skin and the electrodes, and the subjects' age. Though some methods of automatic gain control (AGC) have been developed in the long history of the ECG measurement [4] [5], and most clinical ECG instruments contain the AGC function, these are not suitable for the miniaturization into a battery-powered wearable device because it mostly requires additional pieces of electronic components and/or power-consuming signal processing procedures. In this work, the AGC function is installed with a simple circuit topology and with a simple time-domain algorithm implementable into a microcontroller to maintain a reliable R wave detection even under the above situations.

Figure 2 shows an example of the proposed AGC flow scheme. The gain of the LPF in the analog frontend is controlled by the RC value which is chosen from 32 steps between 0 and  $50 k\Omega$  based on the binary search algorithm. At the beginning of the AGC mode, the RC value is set to  $16 \cdot R_{step}$  (the half value of the maximum  $R_C$ ) where  $R_{step} = 50 k\Omega / 32$ . If the R wave is detected with this gain, the  $R_C$  value is changed to the half between the maximum  $R_C$  and the previous  $R_C$  (e.g.,  $R_C = 24 \cdot R_{step}$ ) to reduce the gain. Subsequently, if the R wave is not detected with the new gain, the  $R_C$  value is changed to the half between the previous  $R_C$  and the  $R_C$  value of two times before (e.g.,  $R_C = 20 \cdot R_{step}$ ) to raise the gain. After this process is repeated six times as shown in Fig. 2, the final gain is decided. This AGC scheme determines the appropriate gain within six steps due to the limitation of the available  $R_C$  values. Because the R wave detection procedure and the  $R_C$  modification only take

approximately 1.5 s and 1 ms, respectively, the whole AGC procedure is finished within 10 s. The AGC procedure is activated when the power of the telemeter is turned ON or the button mounted on the circuit board is pushed.

### C. Wireless Communication and Power Reduction

The RRI telemeter uses the wireless transmission of the RRI data to miniaturize the circuit. To be compatible with the current supply capability of a CR2032 battery and to improve the battery life, the duration of the current consumption during the wireless communication must be minimized. In this work, the telemeter works in three modes: Tx mode, Rx mode, and Standby mode. In the Tx mode, the telemeter transmits the header information and the RRI data within 3 ms with the current consumption of 36 mA and moves to the Rx mode. When the data have been successfully transmitted, the receiver sends back the Success Message and the standby latency (a time length of waiting for the next transmission) to the telemeter. The current consumption of the telemeter is 16 mA during the Rx mode of 3.8 ms. After the bidirectional wireless communication has been finished, the telemeter moves to the Standby mode whose current consumption is 0.1 mA until the next transmission.

To prevent the collision of the multiple telemeters, the transmission timing for each telemeter is predetermined in the receiver, and all the telemeters sequentially acquire the correct timing with the replied standby latency after the initial RRI transmission. In this work, the cycle for the intermittent RF communication of 500 ms was determined on the assumption of multiple use i.e., up to five telemeters.

Throughout the steady state, where the wireless

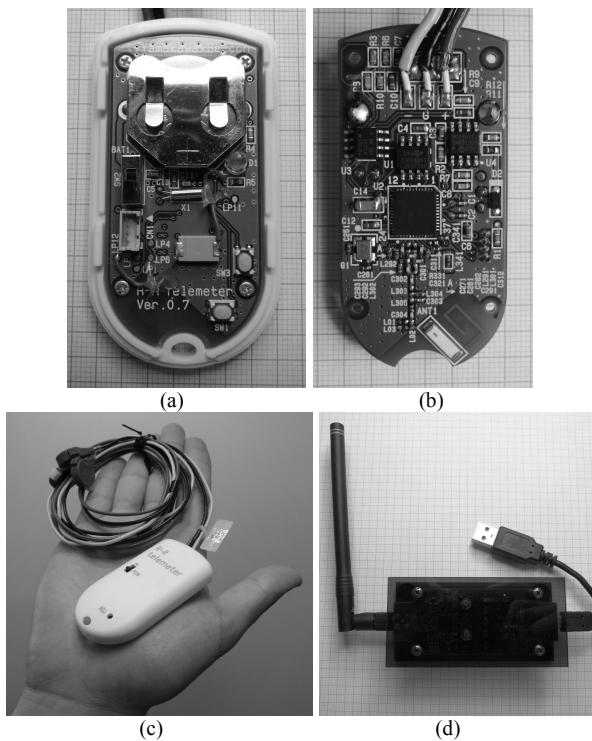


Fig. 3. Photographs of the fabricated circuit board of the RRI telemeter [(a) top and (b) bottom], (c) the telemeter enclosed in a plastic case, and (d) the fabricated receiver.

communication between the telemeter and the receiver is coordinated in the correct timing, the telemeter operates in the Standby mode for 99% of the communication cycle, and thus the mean current consumption is 0.51 mA. This power reduction theoretically enables the continuous operation for more than two weeks (440 h) with a CR2032 battery.

### III. EXPERIMENTAL RESULTS

#### A. Fabrication

The RRI telemeter was fabricated on a four-layer printed circuit board (PCB) of  $30 \times 50$  mm including the case of a CR2032 battery, and was enclosed in a plastic case of  $68 \times 35$  mm with a thickness of 11 mm as shown in Fig. 3 (a)–(c). The cables shown in Fig. 3 (c) are shielded wires connected to the ECG electrodes. Figure 3 (d) is a photograph of the fabricated receiver with a USB cable used for the bus power supply and data transfer to a PC. The circuit board ( $80 \times 40$  mm) is fixed between two acrylic boards instead of the casing. Using low-cost electronic components and the PCB manufacturing technology suitable for mass production, the volume cost of the proposed system, excluding the initial costs of the PCB fabrication, was reduced to less than 200 USD per system.

### B. HRV measurement

The experiments were performed according to the protocols approved by the Research Ethics Committee of Shizuoka University and with the informed consent by the subjects.

To investigate the automatic gain control of the telemeter, five subjects of different ages (5, 21, and 73 year-old females, and 24 and 43 year-old males) were selected to observe how accurately the gain was adjusted to detect the R waves at different ages. The subject's ECG was measured using disposable electrodes (Vitrode Bs-150, Nihon Kohden) in accordance with Lead II. The 21 year-old female (21F) and 24 year-old male (24M) subjects rested in a sitting position, and the 5 year-old female (5F), 43 year-old male (43M), and 73 year-old female (73F) subjects rested in a supine position (mostly sleeping). Figure 4 (a) shows the RRIs of subjects 21F and 24M, and Fig. 4 (b) shows the RRIs of subjects 5F, 43M, and 73F (arbitrary 5 min data points in the middle of the measurement period were sampled in order to highlight the fluctuations of the RRI). The obtained RRIs were compared with the RRIs simultaneously measured by a Holter ECG monitor, and the differences were less than 5 ms, even though the ECG amplitudes varied due to the subjects' age and gender [6]. This indicated that the proposed system has the sufficient temporal precision to monitor the RRIs because the sampling rate of the ECG measurement required for the HRV analysis is higher than 100 Hz [3].

The probability of reoccurring errors was estimated to prove the accuracy and reliability of the R wave detection. The total amount of collecting data of the subject 24M was 2768 for 30 min. In this case, the error region where the RRI data is regarded as the inappropriate value should be under 0.3 s and over 1.3 s. Here, the error region was determined individually for each subject by considering the mean value of

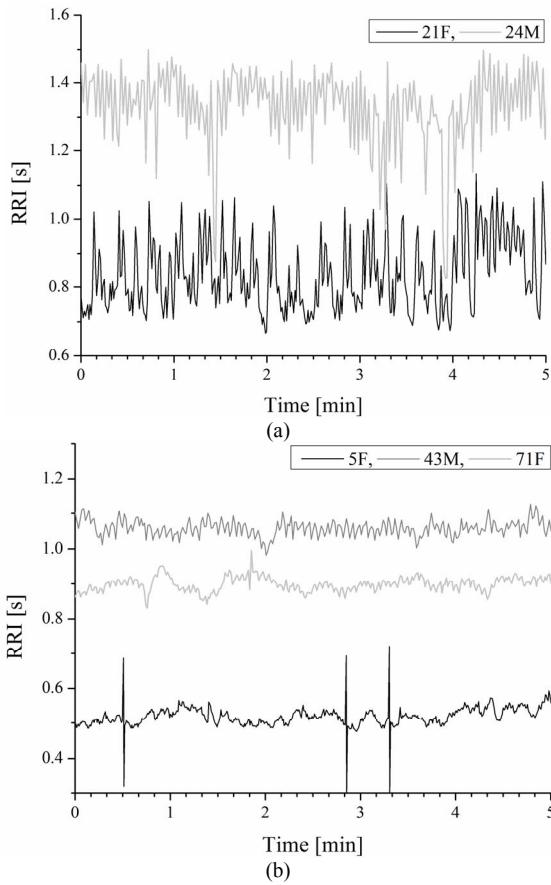


Fig. 4. RRIs measured by the proposed HRV telemetry system (a) in the subjects 21F and 24M, and (b) in the subjects 5F, 43M, and 71F.

the measured RRIs and the expected RRI fluctuation depending on the autonomic function related to the posture of the subject, with the agreement of three medical experts. Eight errors were found within the error region of this subject. The probabilities or reoccurring errors were calculated by dividing the number of errors by the total number of data as the following values: 0.75% for 21F, 0.28% for 24M, 1.33% for 5F, 0.50% for 43M, and 1.63% for 73F. These slim probabilities of errors are negligible because the effect of the errors can be compressed in the frequency analysis commonly used in the HRV analysis [7–10]. The major reason of errors is presumed to be the motion artifacts derived by analyzing the ECG simultaneously recorded by a Holter monitor.

To evaluate the capability of long-term measurements, the accuracy of the RRI detection was quantified for the measurement period of 48 h. The 24 year-old male was selected and the measurement was executed during his daily routines excluding bedtime. The total number of acquired RRI data was 268,312. The probability of recurring errors was calculated as previously mentioned. Its value turned out to be 0.752%, suggesting that the physiological signals in the long-term measurement were successfully detected with minimum errors. Even though an algorithm of the HRV analysis for medical diagnosis or for the evaluation of health status requires to be developed, the proposed system may contribute to make patients unnecessary to be restrained at hospital in order to get a long-term ECG.

#### IV. CONCLUSIONS

A wearable HRV telemetry system equipped with an automatic gain control scheme has been developed for easy use and high accuracy RRI detection toward both clinical care and homecare for subjects with different ages. The desired functions and the validity of the system were proven for subjects different in age and sex. The obtained results showed that the proposed system has a sufficiently low error probability and an adequate temporal resolution for HRV analysis. The fabricated device may contribute to the improvement of quality of healthcare at home with continuous monitoring, and operated by non-experts.

#### ACKNOWLEDGMENT

This research was partially supported by Adaptable and Seamless Technology Transfer Program through Target-driven R&D (231Z04347), Japan Science and Technology Agency, and by JSPS KAKENHI Grant Number 25282175.

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